



Library of Mathematical Transforms over Algorithms of Spectral-Analytical Data Processing

Applications in data analysis and pattern recognition



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Methods

- Generalized Spectral-Analytical Method (GSAM) as extrapolation of classical Fourier series to a wider class of basic approximating functions
- Parallel, recurrent and iterative algorithms of data analysis and transforms

Applications

- Processing of biomechanical experiments data, the control of human state by means of body movements analysis (possible use for driver state recognition)
- Data analysis and diagnosis in electrophysiology (gastrology, cardiology, encephalography)
- Analysis of magnetic encephalography data – the brain functional charting and pathology states control
- Spectral methods of biological macromolecules analysis - genetic sequences, primary and spatial structures of proteins
- Data analysis and recognition in the space surveillance systems
- Monitoring and Diagnostics in the Technical imaging
- Data analysis, modeling and forecasting in the transportation acoustic ecology

Cooperation

- Russian Academy of Sciences –
 - ✓ Institute of Biophysics
 - ✓ Institute of Protein Researches
 - ✓ Dorodnicyn Computing Centre
 - ✓ Blagonravov Institute of Machines Science
 - ✓ Kotel'nikov Institute of Radio-engineering and Electronics
- Lomonosov Moscow State University
- Federal Space Agency
- Russia Tunneling Association
- Moscow SubWay Administration
- Prague Technical University
- New York University
- Berlin Technical University

Grants

- Russian Foundation for Basic Researches
- U.S. Civilian Research and Development Foundation

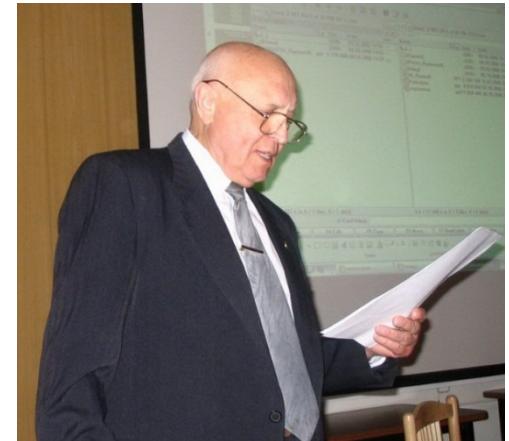
Publications

- F. F. Dedus, S. A. Makhortykh, M. N. Ustinin, and A. F. Dedus. Generalized Spectral-Analytic Method for Data Processing," in Problems in Image Analysis and Pattern Recognition (Mashinostroenie, Moscow, 1999) [in Russian], 356 p.
- F.F.Dedus, S.A.Makhortykh and M.N.Ustinin. Generalized Spectral-Analytic Method in Information Processing Problems. *Pattern Recognition and Image Analysis*, 2002, [vol.12, N 4, pg.429-437.](#)
- A. N. Pankratov, S. A. Makhortykh, et al. Spectral Analysis for Identification and Visualization of Repeats in Genetic Sequences. *Pattern Recognition and Image Analysis*, 2009, Vol. 19, No. 4, pp. 687-692.
- S. Makhortykh, E. Lyzhko. Sources localization for brain biomagnetic activity. *Review of Applied Physics (RAP)*, 2014, vol.3, pg.25-28.
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Classical orthogonal polynomials

Table 1. Classical orthogonal polynomials

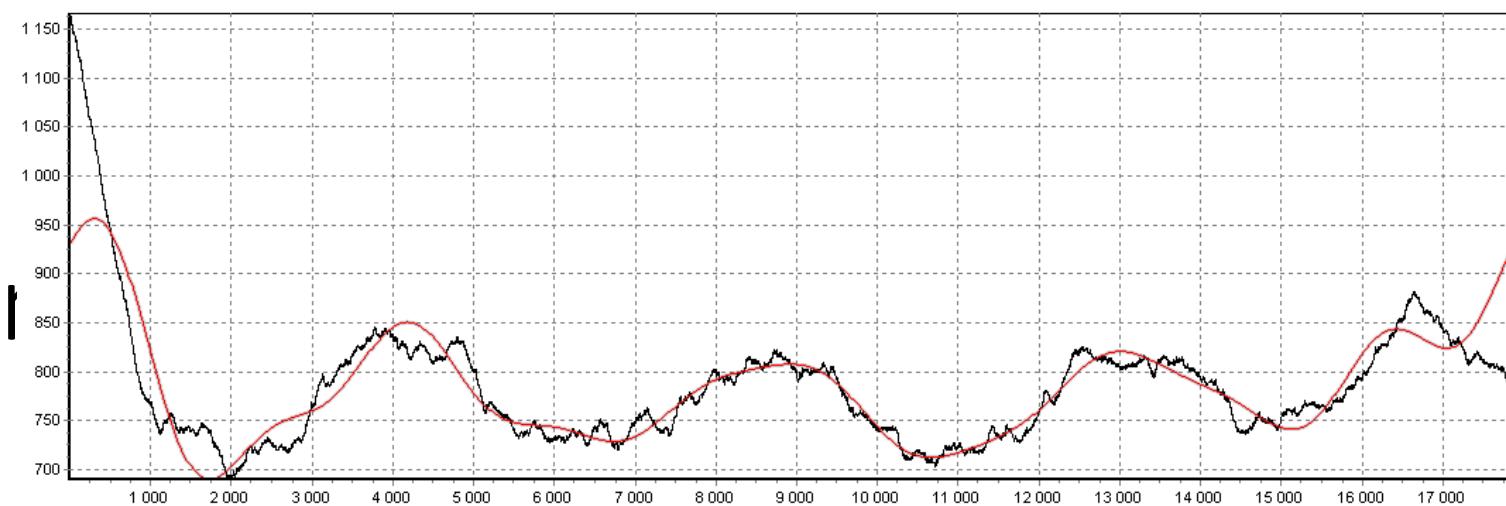
No.	Polynomial	Symbol	General expression	Weight $p(x)$	Limits of existence	
					Lower	Upper
1	Jacobi or hypergeometric	$P_n^{\alpha\beta}(x)$	$P_n^{\alpha\beta}(x) = \frac{1}{2^n} \sum_{k=0}^n C_n^k \frac{\Gamma(\alpha+n+1)}{\Gamma(\alpha+k+1)} \frac{\Gamma(\beta+n+1)}{\Gamma(\beta+n+k+1)} (x-1)^k (x+1)^{n-k}$	$(1-x)^\alpha (1+x)^\beta$ $\alpha > -1 \quad \beta > -1$	-1	+1
2	Gegenbauer of ultraspherical	$C_n^\sigma(x)$	$C_n^\sigma(x) = \sum_{k=0}^n \frac{(-1)^k \Gamma(\alpha+n-k)}{\Gamma(k+1) \Gamma(n-2k+1)} (2x)^{n-2k}$	$(1-x^2)^{\sigma-0.5}$ $\alpha = \beta = \sigma - 0.5$	-1	+1
3	Chebyshev of the first kind	$T_n(x)$	$T_n(x) = \frac{2^n n!}{(2n)!} \sqrt{x^2-1} \frac{d^n}{dx^n} [(x^2-1)^{n-2k}]$	$(1-x^2)^{-0.5}$ $\alpha = \beta = -0.5$	-1	+1
4	Chebyshev of the second kind	$U_n(x)$	$U_n(x) = \frac{2^n (n+1)!}{(2n+1)! \sqrt{x^2-1}} \frac{d^n}{dx^n} [(x^2-1)^{n+0.5}]$	$(1-x^2)^{0.5}$ $\alpha = \beta = 0.5$	-1	+1

Table 2. Classical orthogonal bases of a discrete argument

No.	Orthogonal basis	Symbol	Orthogonal Bases		Saltus function (weight function)	Limits of existence	
			Lower	Upper		Lower	Upper
1	Chebyshev	$\theta_n(t)$	$n! \Delta \left[\binom{t}{n} \binom{t-N}{n} \right]$		1	0	$N-1$
2	Kravchuk's polynomials	$G_n(t; p, q)$	$\frac{(-1)^t}{n!} \frac{(t^n)}{(t-t)!}$	continuous	$\binom{N}{t} p^t q^{N-t}$	0	N
	$\sigma(x)y'' + \tau(x)y' + \lambda_h y = 0$		Polynomial orthogonal bases		Polynomial orthogonal bases		$\sigma(x_i) \nabla \Delta y + \tau(x_i) \Delta y + \lambda_h y = 0$
4	Charlier's polynomials		$\sum_{i=0}^n (-1)^i \frac{n! t! m^i}{i! (n-i)! (t-i)!}$	Bases of classical polynomials	$m > 0$	0	∞
5	Charlier's		$\sqrt{t! m^{i-0.5}} t \exp\left(-\frac{1}{2m}\right) \frac{1}{(t-i)!}$		$m > 0$		∞
6	Meixner's functions	H_n	$P_n^{(\alpha, \beta)}$	Sonin-Laguerre	$I_n^{(\alpha)}$	Kravchuk	$k_n^{(p)}$
7						Han	$h_n^{(\alpha, \beta)}$
8	Hahn's (gibeshev)	Legendre	Tschebyshev I	Tschebyshev II	L_n	Meiksner	$m_n^{(\lambda, \mu)}$
		P_n	T_n	U_n	$\frac{(\beta)_t (\gamma)_t}{(t-n)! (\delta)_{t-n}}$	Charle	$c_n^{(\mu)}$
						Tschebyshev (discrete)	$\ell_n^{(\lambda)}$
							$\frac{(\beta)_t (\gamma)_t}{t! (\delta)_t}$
					*	uniform grid	

Table 3. Orthogonal bases of a continuous argument

No.	Orthogonal basis	Symbol	General expression	Weight $\rho(t)$	Limits of existence	
					Lower	Upper
1	Shifted Jacobi polynomials	$\beta \wedge r_n^{\alpha\beta}(t, T)$	$\sqrt{\frac{(\alpha + \beta + 2n + 1) \Gamma(\alpha + \beta + n + 1) \Gamma(\alpha + n + 1) \Gamma(\beta + n + 1)}{2^{\alpha+\beta} T^n n!}} \frac{1}{T^n} \sum_{k=0}^n \frac{C_n^k (t-T)^k t^{n-k}}{\Gamma(\alpha + k + 1) \Gamma(\beta + n - k + 1)}$	$\frac{2^{\alpha+\beta}}{T^{\alpha+\beta}} (T-t)^{\alpha} t^{\beta}$	0	T
		$\alpha \wedge R_n^{\alpha\beta}(mT)$	$\sqrt{\frac{m (\alpha + \beta + 2n + 1) \Gamma(\alpha + \beta + n + 1) \Gamma(\alpha + n + 1) \Gamma(\beta + n + 1)}{2^{\alpha+\beta} n!}} \sum_{k=0}^n \frac{(-1)^k C_n^k e^{-(0.5+k)mt} (1-e^{-mt})^{n-k}}{\Gamma(\alpha + k + 1) \Gamma(\beta + n - k + 1)}$	$2^{\alpha+\beta} e^{-\alpha mt} (1-e^{-mt})^{\beta}$	0	∞
2	Shifted Jacobi functions	$\beta \wedge r_n^{\alpha\beta}(t, T)$	$\sqrt{\frac{(\alpha + \beta + 2n + 1) \Gamma(\alpha + \beta + n + 1) \Gamma(\alpha + n + 1) \Gamma(\beta + n + 1)}{n! T^{2n+\alpha+\beta+1}}} \sum_{k=0}^n \frac{(-1)^k C_n^k}{\Gamma(\alpha + k + 1)} (T-t)^{\frac{\alpha}{2}+k} t^{\frac{\beta}{2}+n-k}$	1	0	T
		$\alpha \wedge r_n^{\alpha\beta}(mt)$	$\sqrt{\frac{m (\alpha + \beta + 2n + 1) \Gamma(\alpha + \beta + n + 1) \Gamma(\beta + n + 1)}{n!}} \sum_{k=0}^n \frac{(-1)^k C_n^k}{\Gamma(\alpha + k + 1) \Gamma(\beta + n - k + 1)} e^{-\frac{\alpha+1+2k}{2}mt} (1-e^{-mt})^{n-k}$	1	0	∞
3	Shifted Gegenbauer polynomials	$C^\sigma(t, T)$	$\sqrt{\frac{(\sigma+n) \Gamma(2\sigma+n)}{2^{2\sigma-2} T^n n!}} \Gamma(\sigma+n+0.5) \frac{1}{T^n} \sum_{k=0}^n \frac{C_n^k (t-T)^k t^{n-k}}{\Gamma(\sigma+k+0.5) \Gamma(\sigma+n-k+0.5)}$	$\frac{2^{2\sigma-1}}{T^{2\sigma-1}} (T-t)^{\sigma-0.5} t^{\sigma-0.5}$	0	T
		$C^\sigma(mt)$	$\sqrt{\frac{m (\sigma+n) \Gamma(2\sigma+n)}{2^{2\sigma-2} n!}} \Gamma(\sigma+n+0.5) \sum_{k=0}^n \frac{(-1)^k C_n^k e^{-(0.5+k)mt}}{\Gamma(\sigma+k+0.5) \Gamma(\sigma+n-k+0.5)} (1-e^{-mt})^{n-k}$	$2^{2\sigma-1} e^{-(\sigma-0.5)mt} \times (1-e^{-mt})^{\sigma-0.5}$	0	∞

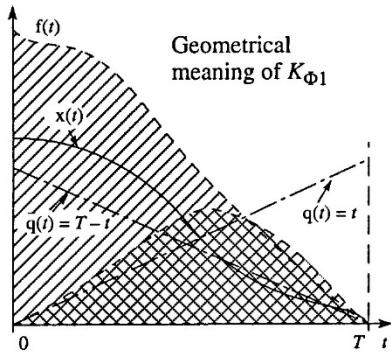


$$x(t) = \sum_{n=0} A_n \varphi_n(t)$$

$\varphi_n(t)$ - functional orthogonal basis



Form coefficient

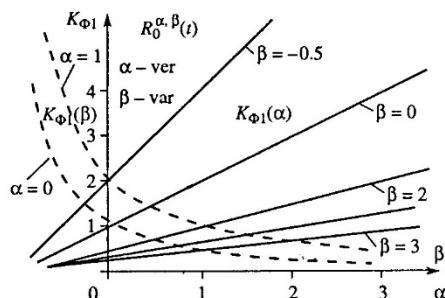
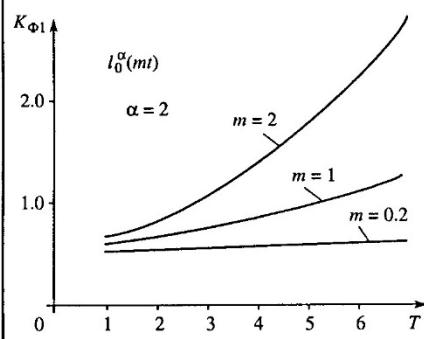
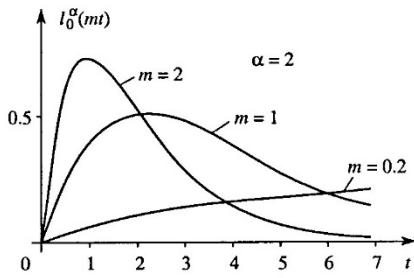


$$K_{\Phi q} = \frac{\bar{J}_q}{J_q} = \frac{\int_0^T x(t) \bar{q}(t) dt}{\int_0^T x(t) q(t) dt}; \quad K_{\Phi q} = \frac{\sum_{t=0}^N x(t) \bar{q}(t)}{\sum_{t=0}^N x(t) q(t)}$$

t – continuous argument, t – discrete argument.

$x(t)$ – the signal

$q(t)$ – known function



For $q(t) = t^n$, $\bar{q}(t) = (T-t)^n$

For $q(t) = e^{-at}$, $\bar{q}(t) = e^{-a(T-t)}$

$$K_{\Phi n} = \frac{\int_0^T x(t) (T-t)^n dt}{\int_0^T x(t) t^n dt}, \quad K_{\Phi e} = \frac{\int_0^T x(t) e^{-a(T-t)} dt}{\int_0^T x(t) e^{-at} dt}$$

power form coefficient

exponential form coefficient

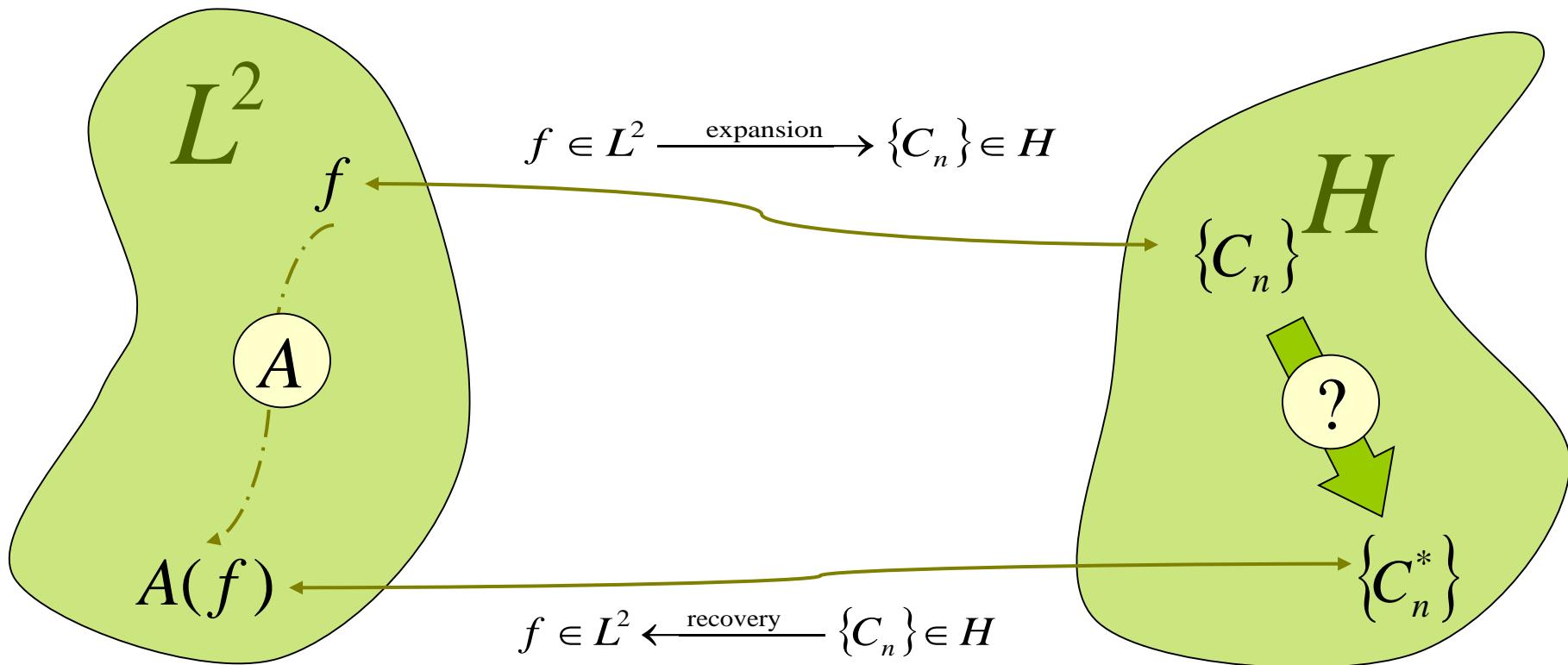
$$K_{\Phi 1} = \frac{\int_0^T x(t) (T-t) dt}{\int_0^T x(t) t dt} = \frac{T \int_0^T x(t) dt - \int_0^T x(t) t dt}{\int_0^T x(t) t dt} = T \frac{J_0}{J_1} - 1.$$

If $K_{\Phi 1} > 1$, then $x(t)$ – decays on $[0, T]$;

If $K_{\Phi 1} < 1$, then $x(t)$ – increases on $[0, T]$;

If $|K_{\Phi 1}| \approx 1$, then $x(t)$ – is periodical (nondecreasing).

Transformations in the space of coefficients



Long-term numerical computation

$$f(x) \xrightarrow{\text{Digital transformations } A()} A(f(x))$$

The acceleration

$$\{C_n\} \xrightarrow{\text{How to calculate?}} \{C_n^*\}$$

$$\hat{L} = \frac{d^k}{dx^k} + a_1 \frac{d^{k-1}}{dx^{k-1}} + \dots + a_{k-1} \frac{d}{dx} + a_k$$

$$\hat{L}y = f$$

$$\left.\hat{g}y\right|_s = f_0$$

$$\hat{g} = \frac{d^{k-1}}{dx^{k-1}} + b_1 \frac{d^{k-2}}{dx^{k-2}} + \dots + b_{k-2} \frac{d}{dx} + b_{k-1}.$$

$$y = \sum_{i=0}^N p_i T_i, \quad f = \sum_{i=0}^N h_i T_i \quad \text{и} \quad \left. \sum_{i=0}^N a_i \hat{g} T_i \right|_s = f_0$$

Derivative approximation

$$y'_N(t) = \sum_{i=0}^N d_i^{(1)} T_i(t),$$

$$\mathbf{d}^{(1)} = \mathbf{D}_N \mathbf{p},$$

$$\mathbf{d}^{(k)} = \mathbf{D}_{N-k+1} \cdot \dots \cdot \mathbf{D}_N \mathbf{p}.$$

$$\hat{L} \quad \left\{ d_{ij}^{(\hat{L})} \right\} = \left\{ d_{ij}^{(k)} + a_1 d_{ij}^{(k-1)} + \dots + a_{k-1} d_{ij}^{(1)} + a_k \right\}$$

Derivative approximation in Chebyshev basis

$$\mathbf{D}_N = N-1 \begin{pmatrix} 0 & \begin{matrix} \sqrt{2} & 0 & 3\sqrt{2} & 0 & 5\sqrt{2} & \dots \end{matrix} \\ & \begin{matrix} 0 & 4 & 0 & 8 & 0 & \dots \end{matrix} \\ & \begin{matrix} 0 & 0 & 6 & 0 & 10 & \dots \end{matrix} \\ & \ddots & \ddots & \ddots & \ddots & \ddots \\ & 0 & 0 & \dots & 0 & 0 & 2N \end{pmatrix}$$

$$b_0 = \sqrt{2}p_1 + 3\sqrt{2}p_3 + 5\sqrt{2}p_5 + \dots + N\sqrt{2}p_N$$

$$b_1 = 4p_2 + 8p_4 + 12p_6 + \dots + 2(N-1)p_{N-1}$$

$$b_2 = 6p_3 + 10p_5 + 14p_7 + \dots + 2Np_N$$

.....

$$b_{N-1} = 2Np_N$$

Derivative approximation in Legendre basis

$$D_N = N-1 \left\{ \begin{array}{c|cccccc} & \overbrace{\sqrt{3} & 0 & \sqrt{7} & 0 & \sqrt{11} & \dots} \\ \hline 0 & 0 & \sqrt{3}\sqrt{5} & 0 & \sqrt{3}\sqrt{9} & 0 & \dots \\ & 0 & 0 & \sqrt{5}\sqrt{7} & 0 & \sqrt{5}\sqrt{11} & \dots \\ & & & \ddots & & & \\ & & & & \ddots & & \\ & 0 & 0 & \dots & 0 & 0 & \sqrt{2N-1}\sqrt{2N+1} \end{array} \right\}$$

Example

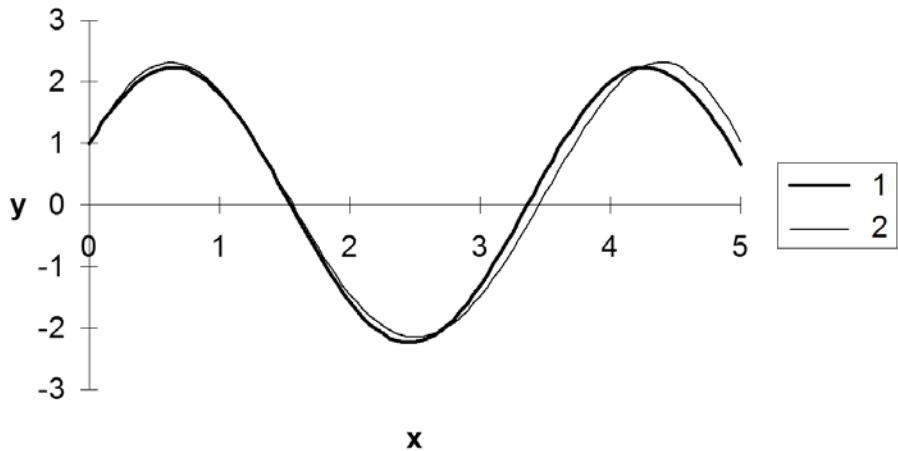
$$u'' + 3u = 0,$$

$$u(0) = 1,$$

$$u'(5) = 2\sqrt{3} \cos(5\sqrt{3}) - \sqrt{3} \sin(5\sqrt{3}).$$

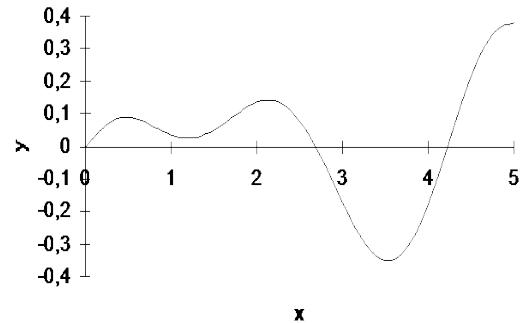
$$u(x) = \cos(\sqrt{3}x) + \sin(\sqrt{3}x).$$

N=8

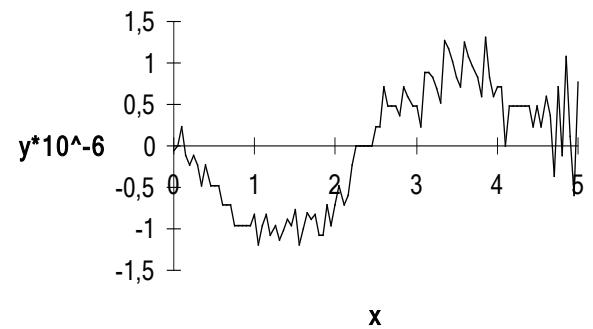


$$u(x) = \sum_{k=0}^{N=8,16} A_k \varphi_k(x)$$

N=8



N=16



$$f(x) = \int y(x) dx$$

$$\mathbf{b} = \mathbf{I}_n \mathbf{h}$$

$$\mathbf{b} = \begin{pmatrix} \beta_1 \\ \beta_2 \\ \dots \\ \beta_N \end{pmatrix} \quad \mathbf{h} = \begin{pmatrix} \eta_1 \\ \eta_2 \\ \dots \\ \eta_N \end{pmatrix}$$

$$\mathbf{I}_N = N \left\{ \begin{array}{cccccc} \frac{1}{\sqrt{2}} & 0 & -\frac{1}{2} & 0 & 0 & \dots \\ 0 & \frac{1}{4} & 0 & -\frac{1}{4} & 0 & \dots \\ 0 & 0 & \frac{1}{6} & 0 & -\frac{1}{6} & \dots \\ \vdots & & \vdots & & & \dots \\ 0 & 0 & \dots & 0 & 0 & \frac{2}{2(N+1)} \end{array} \right\}$$

$$\beta_1 = \frac{\eta_0}{\sqrt{2}} - \frac{\eta_2}{2},$$

$$\beta_2 = \frac{\eta_1}{4} - \frac{\eta_3}{4},$$

$$\beta_3 = \frac{\eta_2}{6} - \frac{\eta_4}{6},$$

.....

$$b_{N+1} = \frac{1}{2N+1} \eta_N$$

Wiener-Hopf equation

$$u(x) - \int_0^\infty R(x-s) u(s) ds = f(x)$$

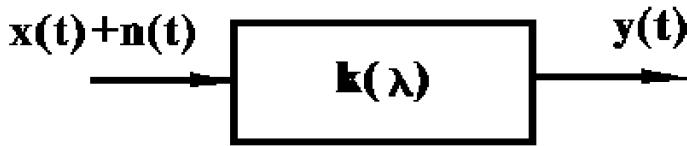
$$R(x) = R_1(x) + \delta(x),$$

$$f_1(x) = -f(x)$$

$$\int_{-\infty}^{+\infty} \varphi(s) \delta(x-s) ds = \varphi(x)$$

$$\int_0^\infty R_1(x-s) u(s) ds = f_1(x)$$

$$R_{xy}(\tau) = \int_0^{\infty} R_{xx}(\tau - \lambda) k(\lambda) d\lambda,$$



$$y(t) = \int_0^t x(t-\tau) k(\tau) d\tau.$$

$$R_{xx}(\tau) = \sum_{i=0}^N C_i l_i(m\tau),$$

$$R_{xy}(\tau) = \sum_{i=0}^N D_i l_i(m\tau).$$

$$k(\lambda) = \sum_{i=0}^N E_i l_i(m\tau)$$

l_i - i^{th} Laguerre function with parameter $m > 0$

$$\begin{aligned} R_{xy}(\tau) &= \int_0^{\infty} R_{xx}(\tau) k(\lambda) d\lambda = - \int_{-\infty}^{\infty} R_{xx}(\tau) k(\tau - \lambda) d\lambda = \\ &= \int_{-\infty}^0 R_{xx}(\tau) k(\tau - \lambda) d\lambda + \int_0^{\tau} R_{xx}(\lambda) k(\tau - \lambda) d\lambda. \end{aligned}$$

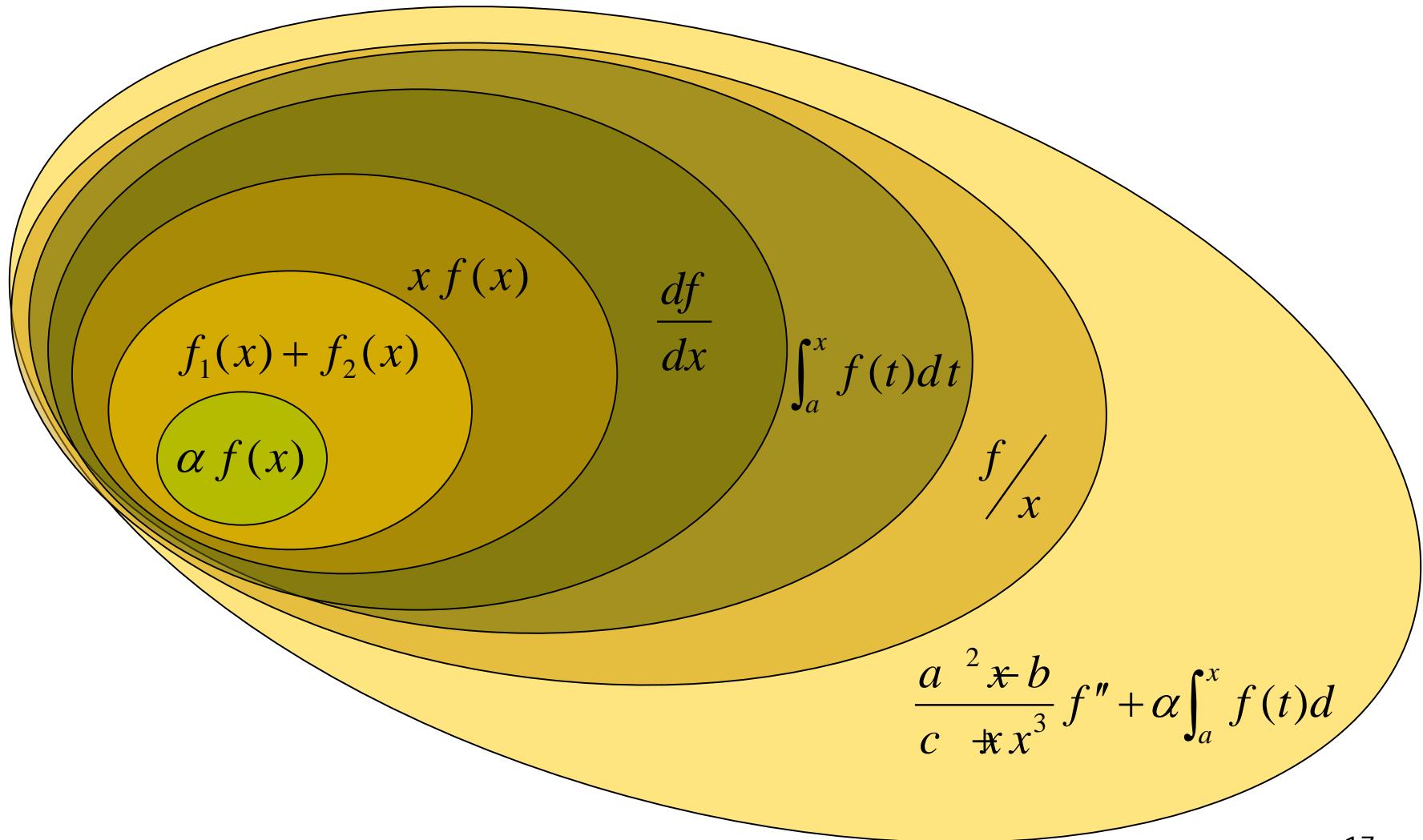
$$\begin{aligned} \int_{-\infty}^0 R_{xx}(\lambda) k(\tau - \lambda) d\lambda &= \int_{-\infty}^0 R_{xx}(-\lambda) k(\tau + \lambda) d(-\lambda) = \\ &= \int_0^{\infty} R_{xx}(-\lambda) k(\tau + \lambda) d\lambda = \int_0^{\infty} R_{xx}(\lambda) k(\tau + \lambda) d\lambda. \end{aligned}$$

$$\int_0^{\infty} R_{xx}(\lambda) k(\tau + \lambda) d\lambda = \sum_{p=0}^N C_p \sum_{j=0}^N E_j \int_0^{\infty} I_p(m\lambda) I_j(m\tau + m\lambda) d\lambda.$$

$$I_n(m(x+y)) = \frac{1}{\sqrt{m}} \sum_{j=0}^n I_j(mx) \{ I_{n-j}(my) - I_{n-j-1}(my) \}$$

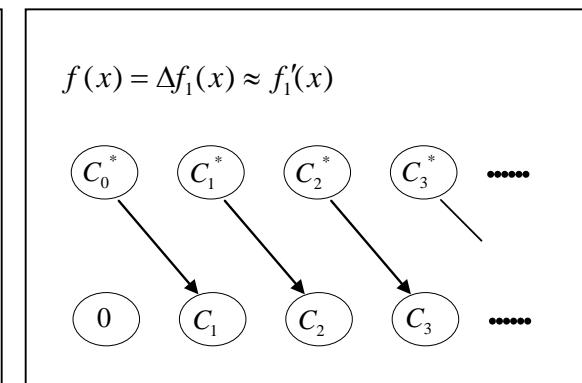
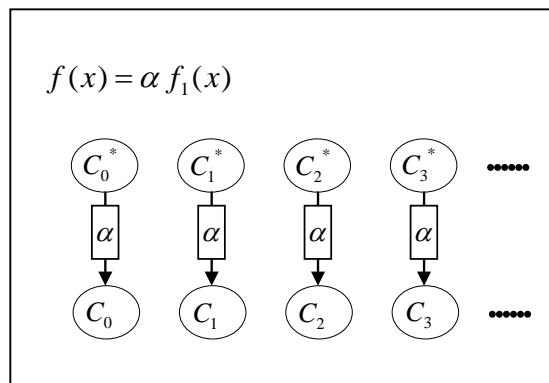
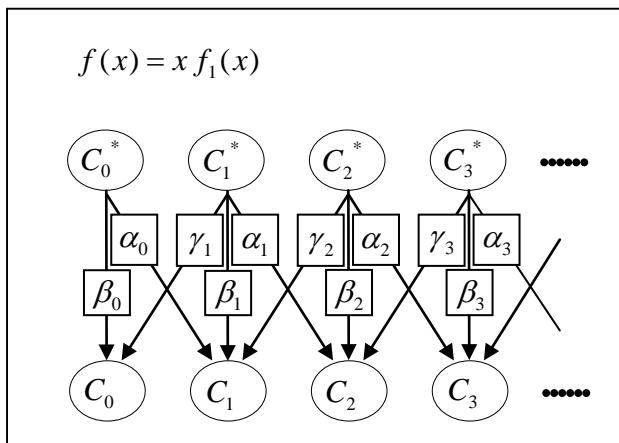
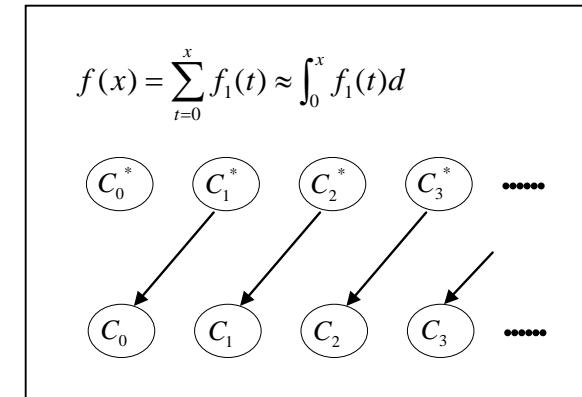
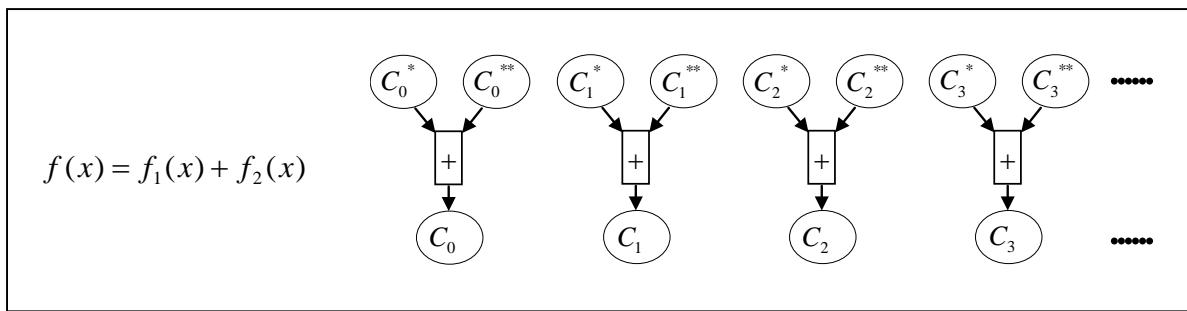
$$\begin{aligned} \sqrt{m} D_i &= C_0 E_i + \sum_{j=0}^N E_j (C_{|i-j|} - C_{|i-j|-1}), \\ C_i &\equiv 0 \text{ for } \forall i < 0, \end{aligned}$$

Operators, realized as a quick 'autospectral' algorithms



Recurrent calculations of coefficients. The method of fast series transformation $O(N)$

Analytical transformations and the corresponding changes in the spectral coefficients using orthogonal polynomials of Kravchuk



Parallel computing for the ultrafast transformation of spectral series $O(\ln N)$

Functional calculation

$$f = \int (\alpha f'_1 + x^2 f_2) dx$$

$$f(x) \approx \sum_{t=0}^x (\alpha \Delta f_1(t) + x^2 f_2(t))$$

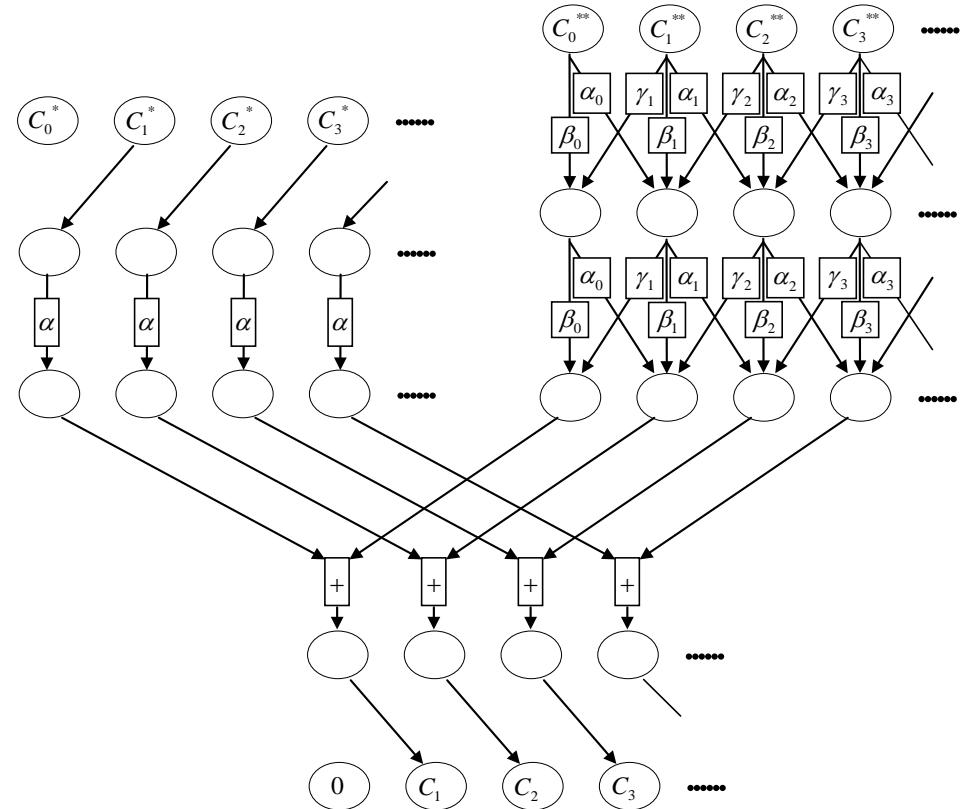
By means of expansion coefficients

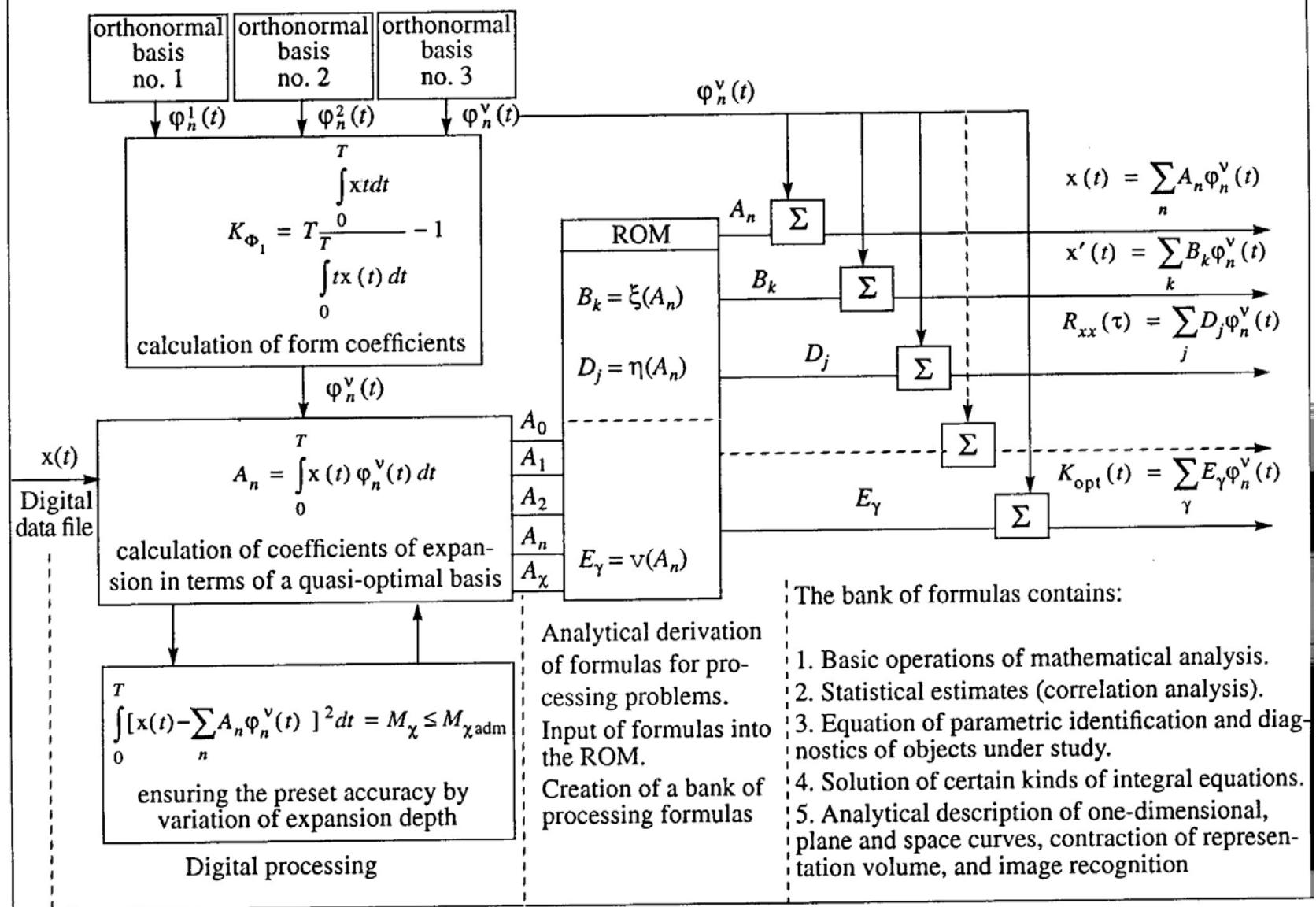
Spectra of f_1 and f_2 :

and $\{C_0^*, C_1^*, C_2^*, \dots\}$
 $\{C_0^{**}, C_1^{**}, C_2^{**}, \dots\}.$

Result – spectrum of $f(x)$:

$$\{C_0, C_1, C_2, \dots\}$$





$$N = N_{\min}$$

$$x(t) \approx \sum_{n=0}^{N_{\min}} A_n \varphi_n(t)$$

IMAGE ANALYSIS AND PATTERN RECOGNITION

Parametric representation of space curves

$$\left. \begin{array}{l} x = x(t) \\ y = y(t) \\ z = z(t) \end{array} \right\} \quad \text{The vector form}$$

$$\mathbf{F} = i x(t) + j y(t) + k z(t)$$

$$x(t) = \sum_{n=0}^N A_n \varphi_n(t);$$

$$y(t) = \sum_{k=0}^K B_k \psi_k(t);$$

$$z(t) = \sum_{i=0}^J C_i \eta_i(t);$$

The root-mean-square error of the approximation:

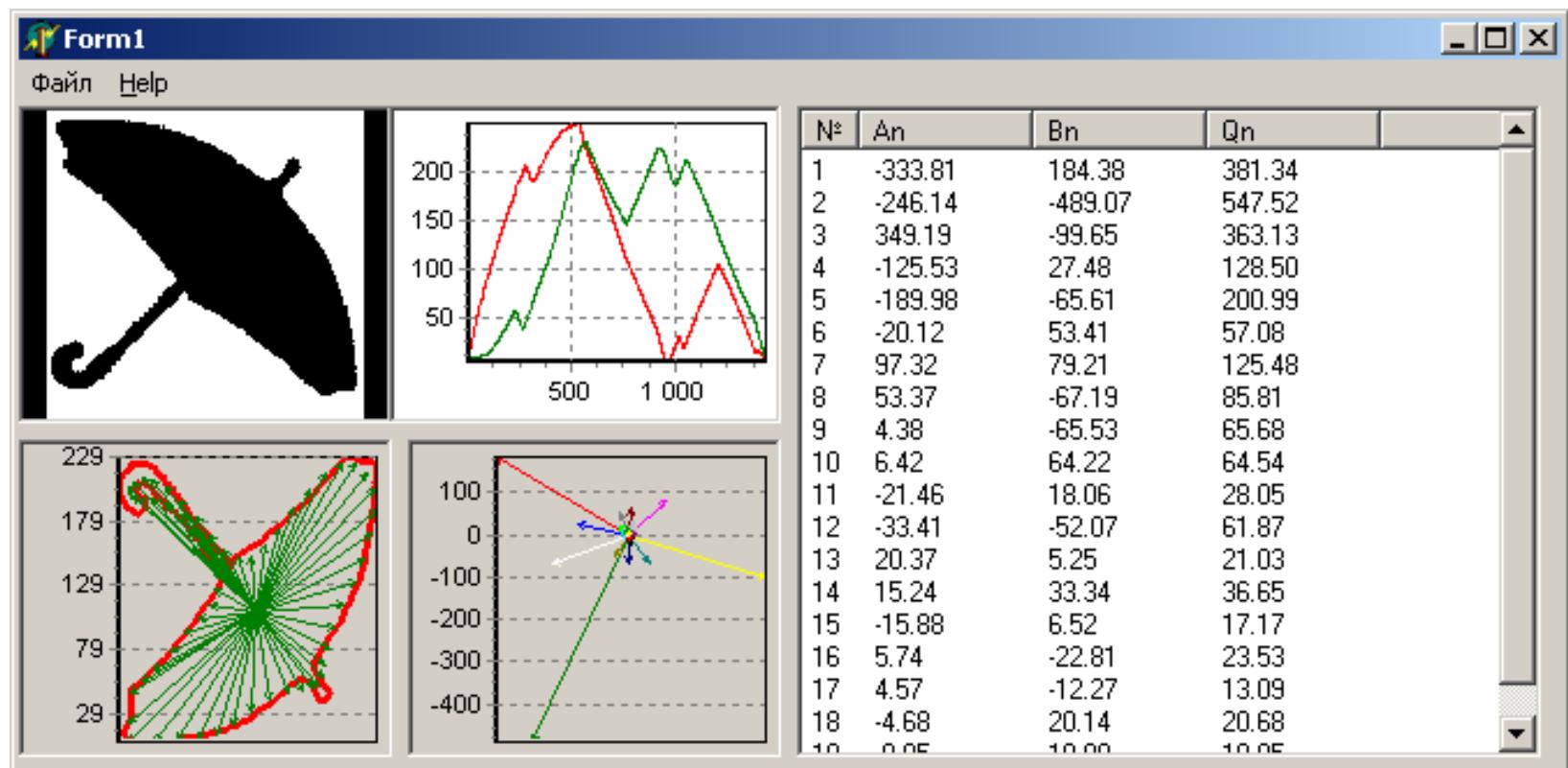
$$\theta_n = \frac{\int_a^b \left[x(t) - \sum_{n=0}^N A_n \varphi_n(t) \right]^2 dt}{\int_a^b x^2(t) dt}$$

$$= 1 - \frac{\sum_{n=0}^N A_n^2}{\int_a^b x^2(t) dt}.$$

or accuracy:

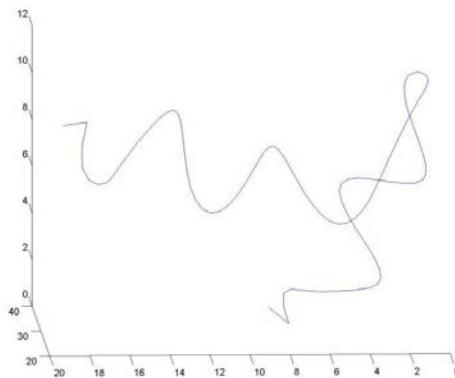
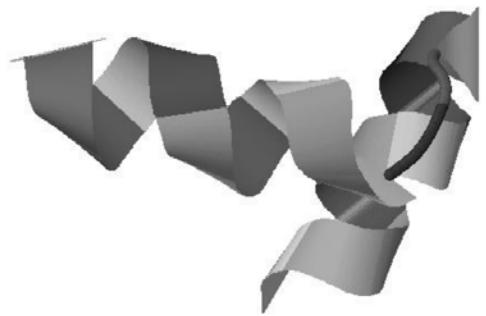
$$\gamma_n = 1 - \theta_n = \frac{\sum_{n=0}^N A_n^2}{\int_a^b x^2(t) dt} = \frac{\sum_{n=0}^N A_n^2}{B_x}.$$

Analytical description of contours and selection of analytical features

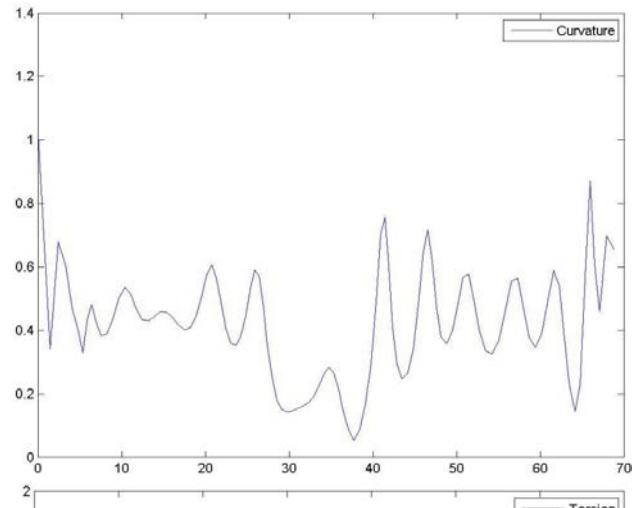


Software for OCR

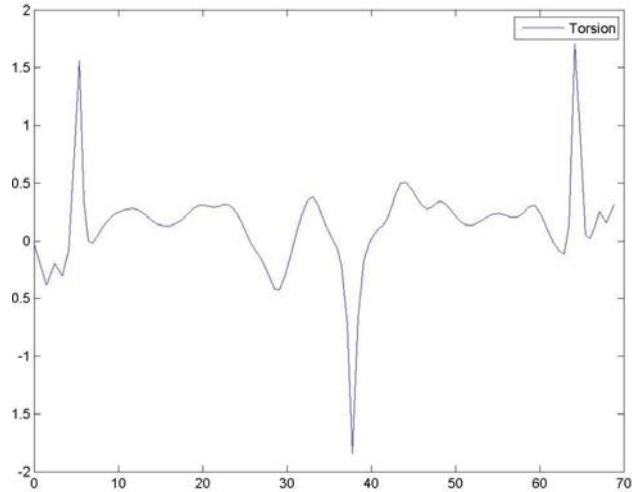




$$\begin{cases} x = x(t), \\ y = y(t), \\ z = z(t) \end{cases}$$



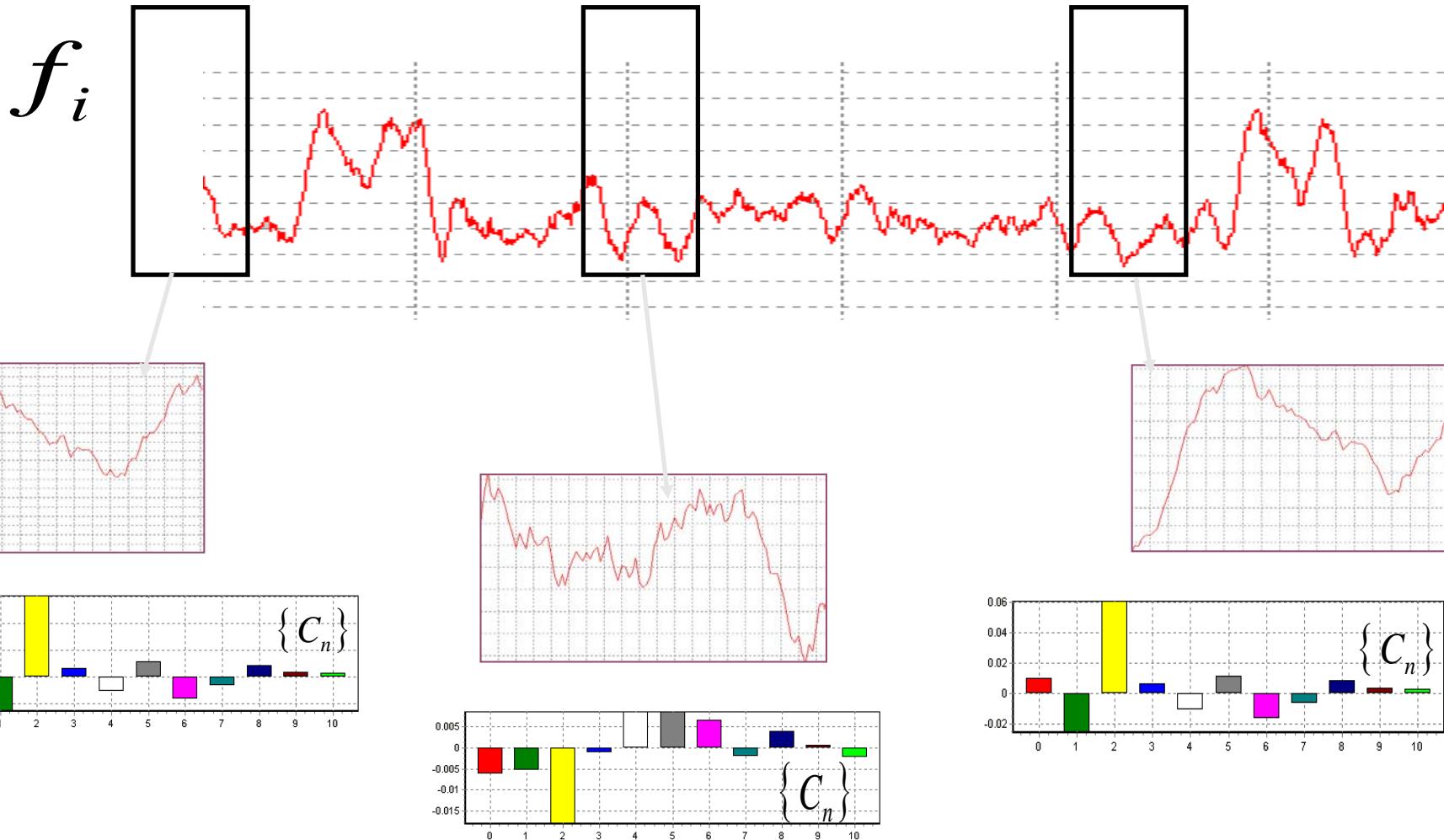
$$\begin{cases} C(s) = \sqrt{\ddot{x}^2 + \ddot{y}^2 + \ddot{z}^2}, \\ \begin{vmatrix} \dot{x} & \dot{y} & \dot{z} \\ \ddot{x} & \ddot{y} & \ddot{z} \\ \ddot{\ddot{x}} & \ddot{\ddot{y}} & \ddot{\ddot{z}} \end{vmatrix} \\ T(s) = \frac{\ddot{x}^2 + \ddot{y}^2 + \ddot{z}^2}{C(s)} \end{cases}$$



$$\begin{cases} x(t) = \sum_{i=0}^N A_i \phi_i(t) \\ y(t) = \sum_{i=0}^N B_i \phi_i(t) \\ z(t) = \sum_{i=0}^N C_i \phi_i(t) \end{cases}$$

Repeats search in genomes

АТГХГХАТТХТХТГХХХТГХАТААААТХГХХГТАТААААХХГХТАХ



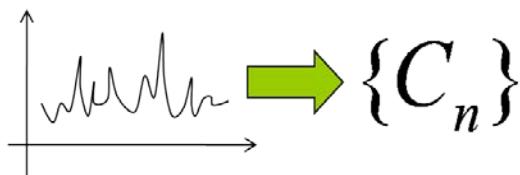
General scheme of the algorithm

actg**NNN**tgca
actgtgca

Preliminary DNA processing
последовательностей



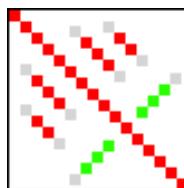
Preparation of DNA
profiles : GC%, GA%



Converting the DNA profiles
in the spectral representation

$$\theta(\{C_n\}, \{C'_n\}) < \varepsilon$$

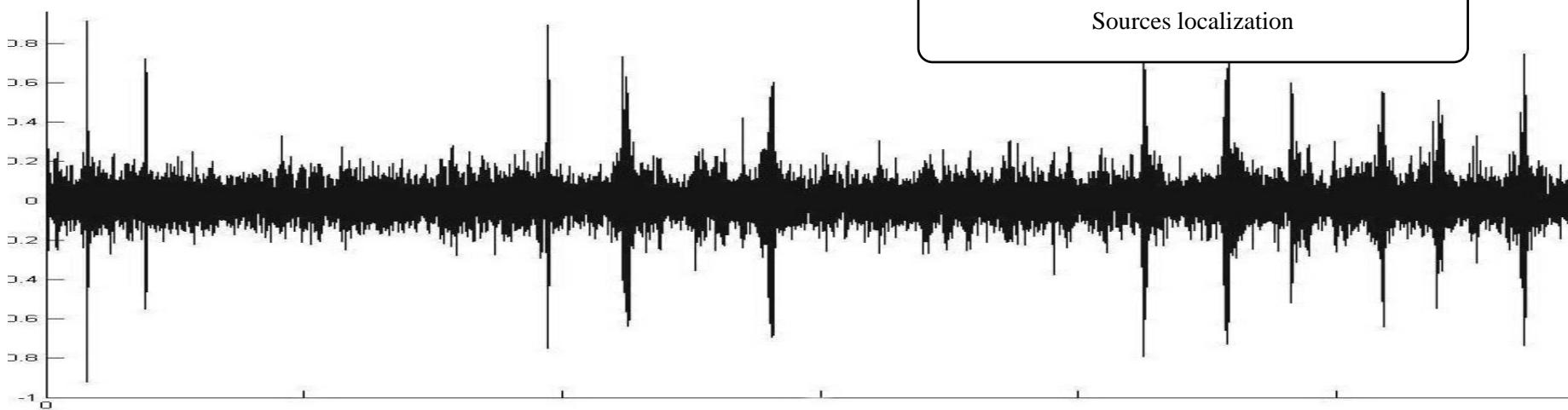
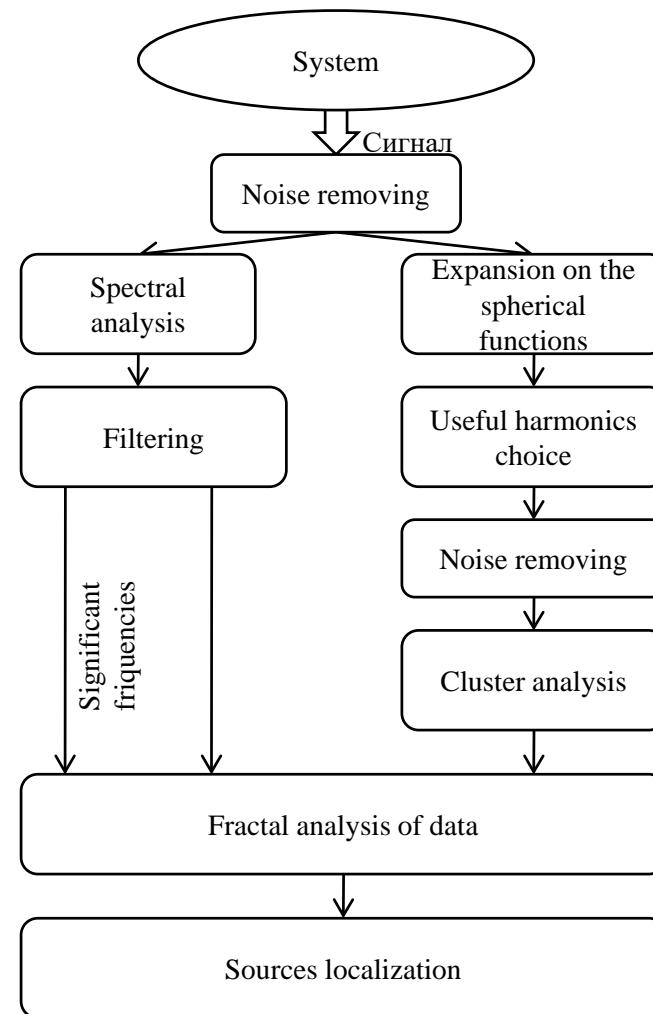
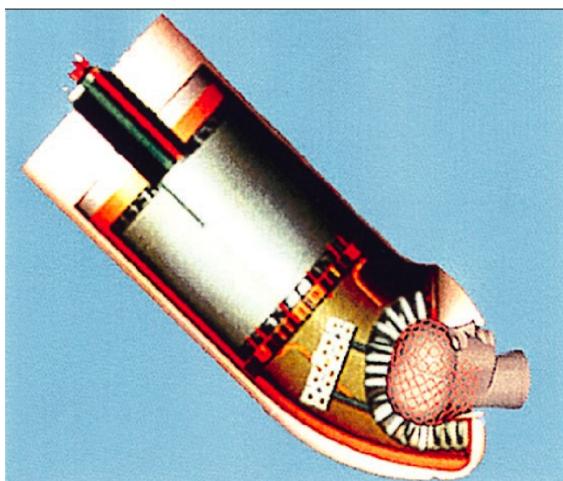
Comparison of the
spectra
of DNA fragments profiles



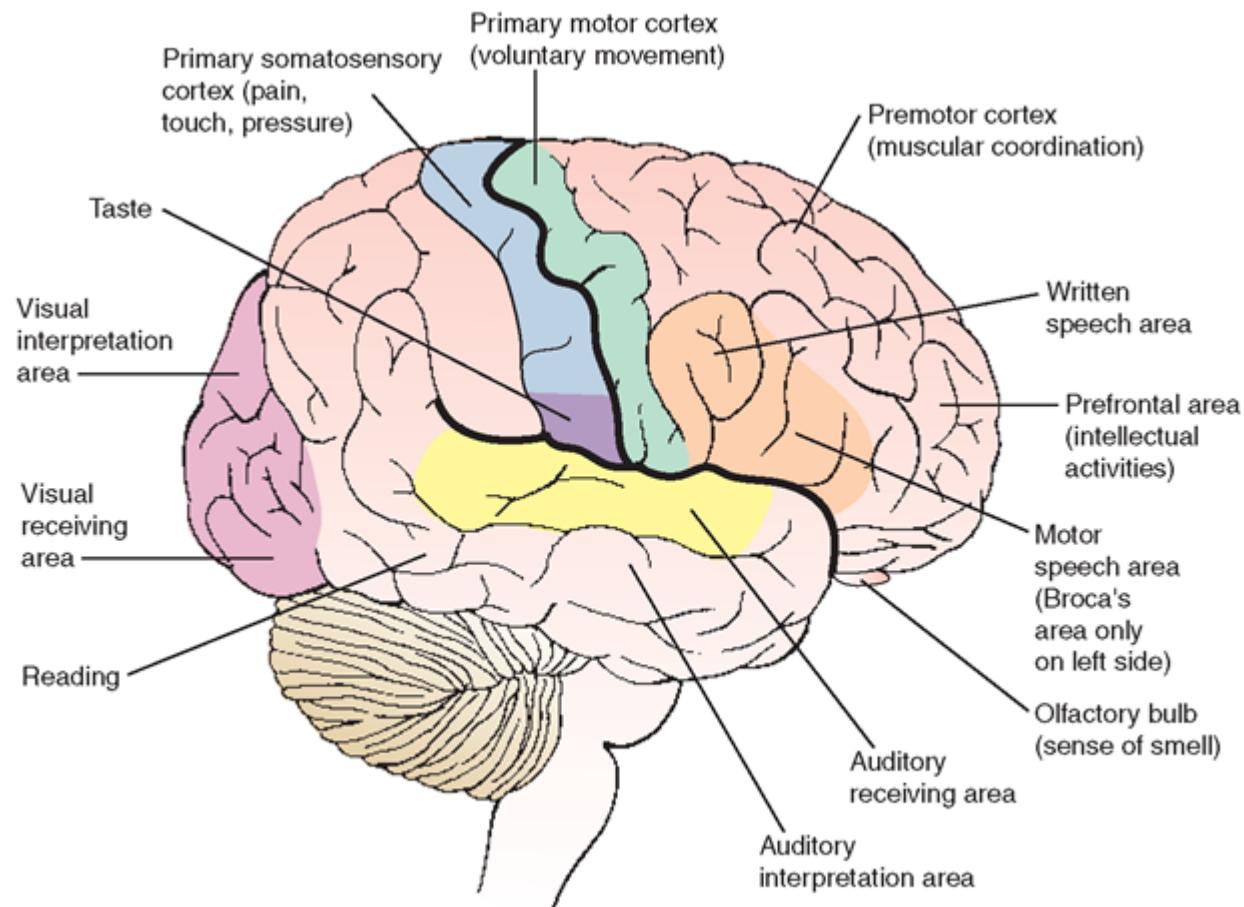
Showing results in the matrix of
spectral similarity and analysis

Magnetic encephalography

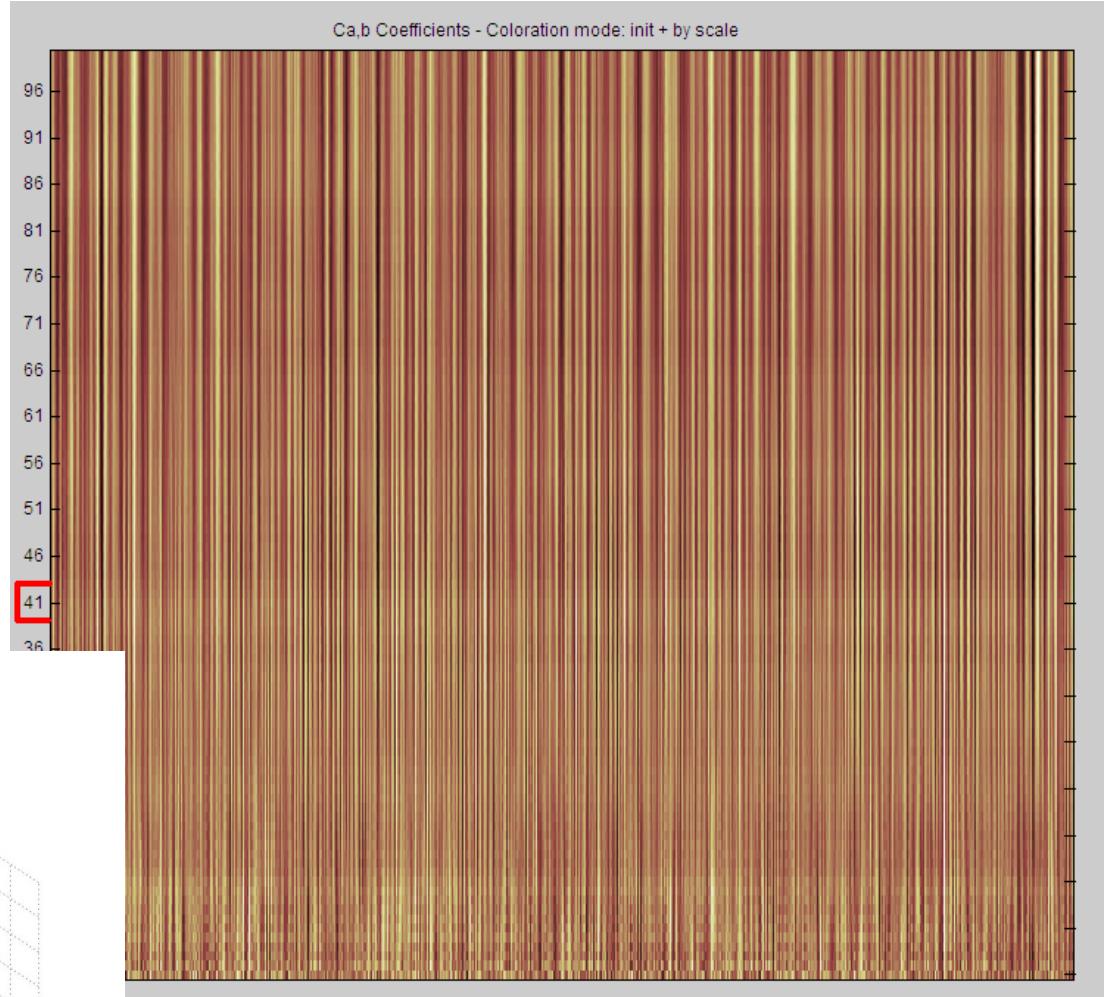
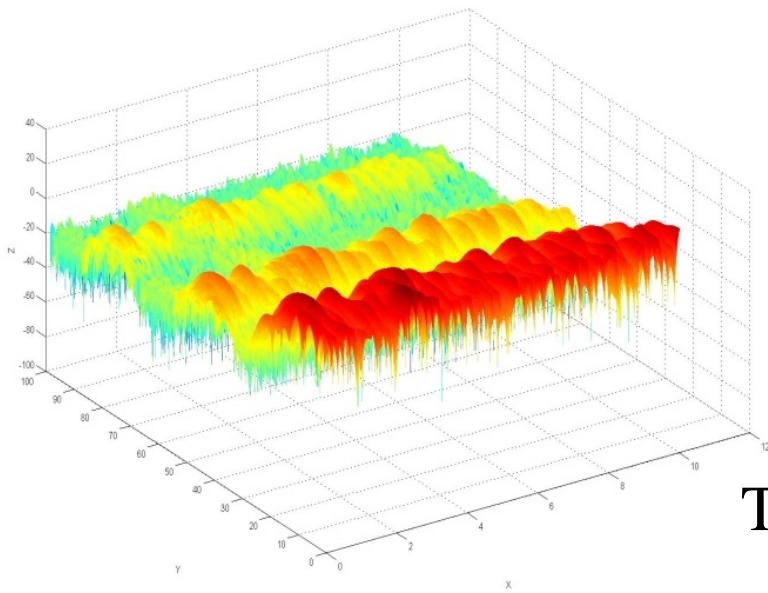
Measuring complex Magne 2500 WH
(New York, USA)



The brain functional areas mapping



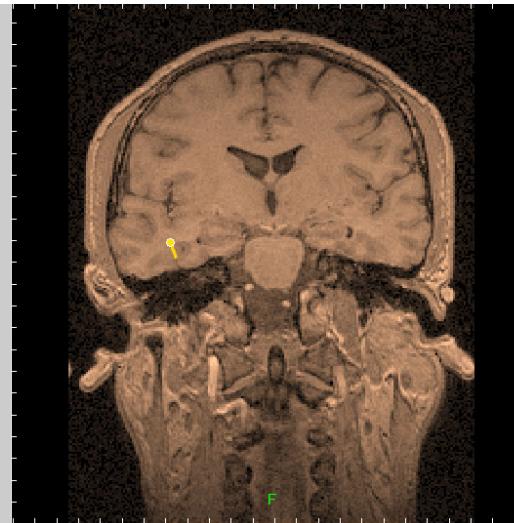
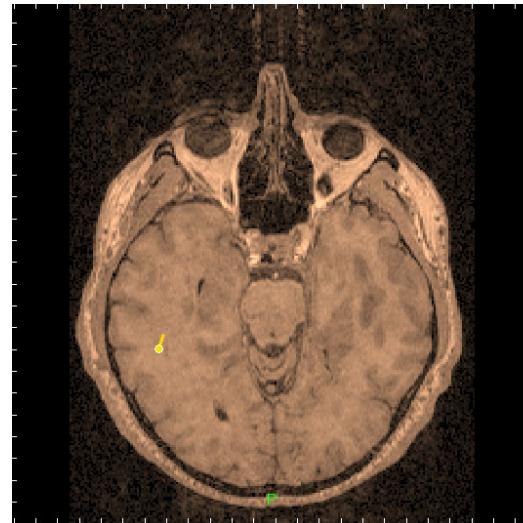
Audio stimulation



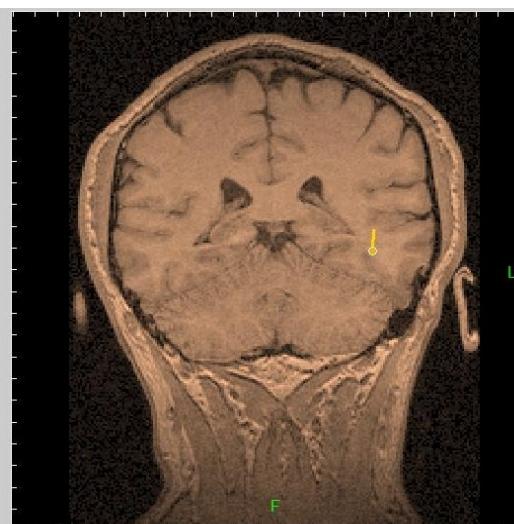
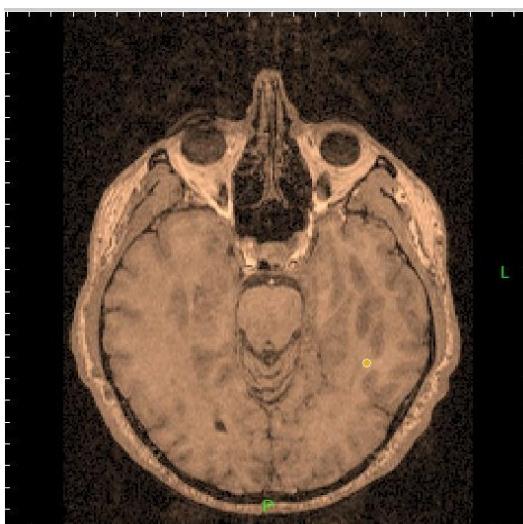
The wavelet coefficients in the Haar basis

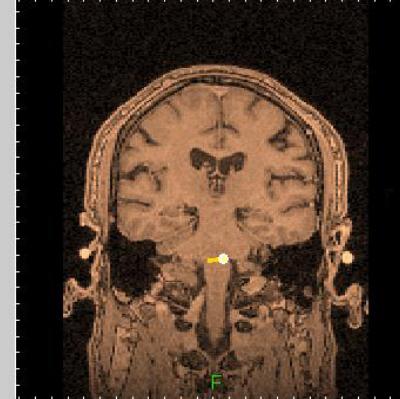
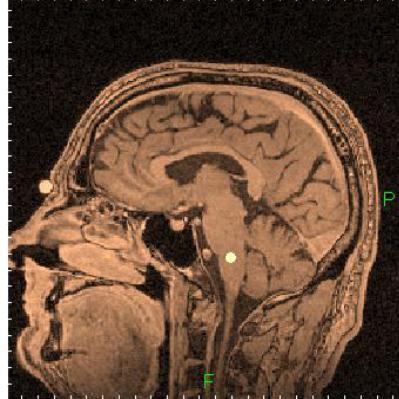
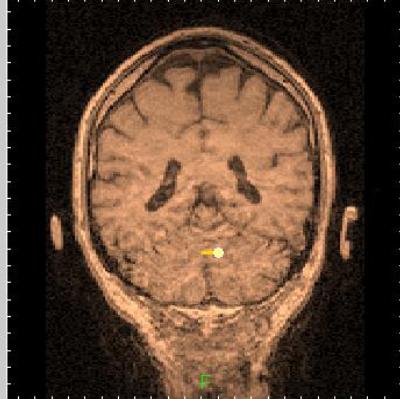
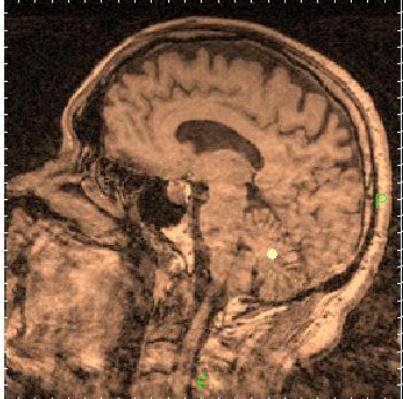
Localization of the source feeding the audio stimulus

localization of the magnetic field source at 10 Hz



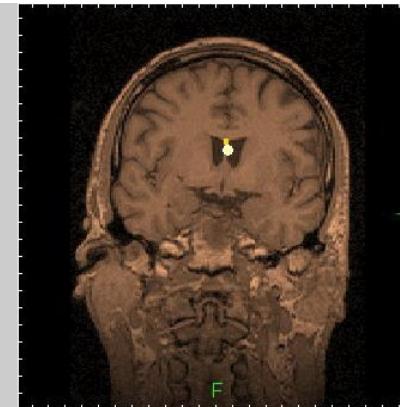
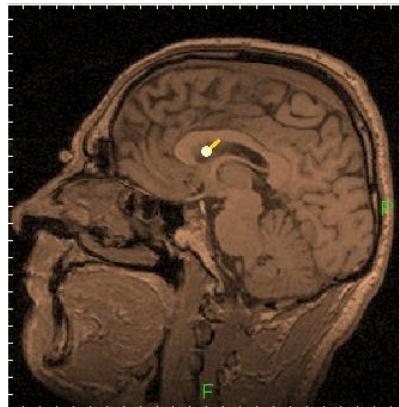
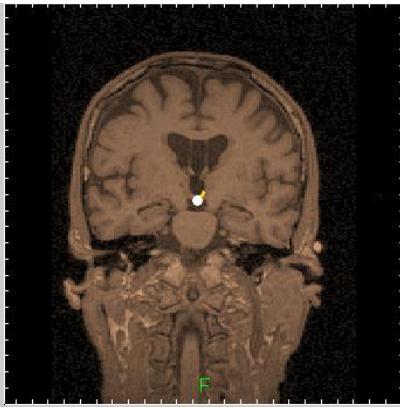
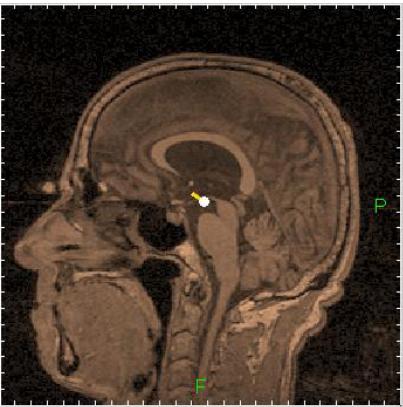
20 Hz





a source in the cerebellum

... in the brainstem (pons)



... in substantia nigra

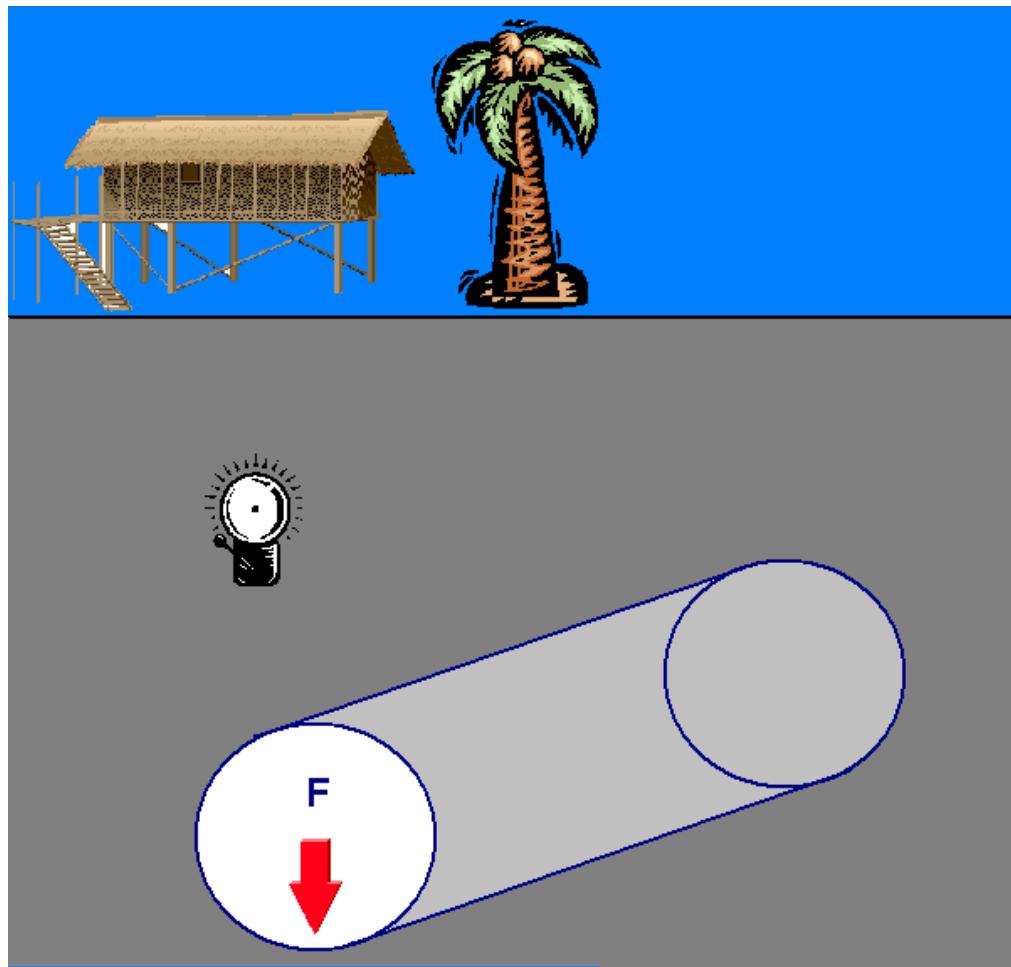
... in the caudate nucleus

Parkinsonism

Vibro-acoustic ecology of the city



The problem of vibro-acoustic control



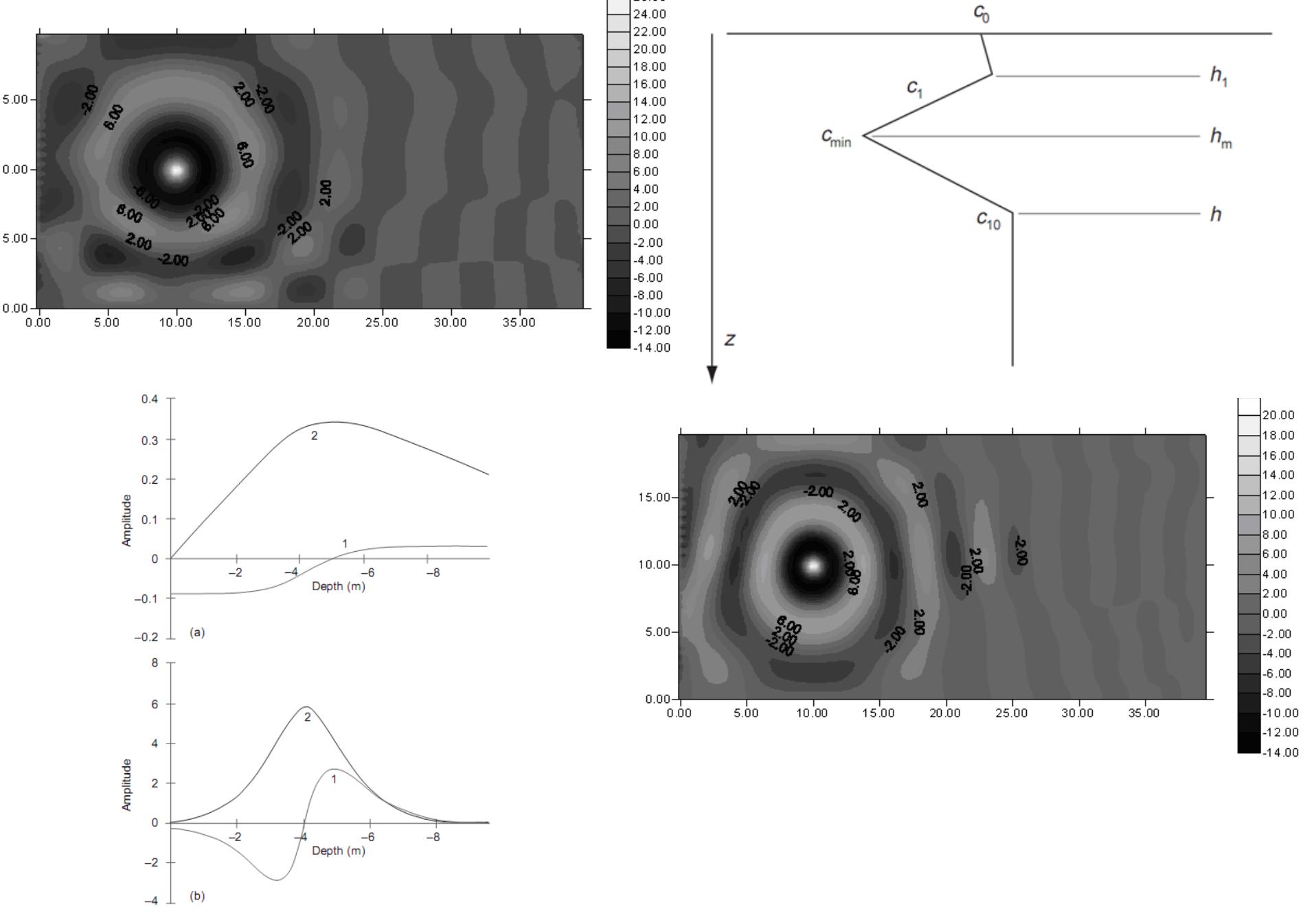
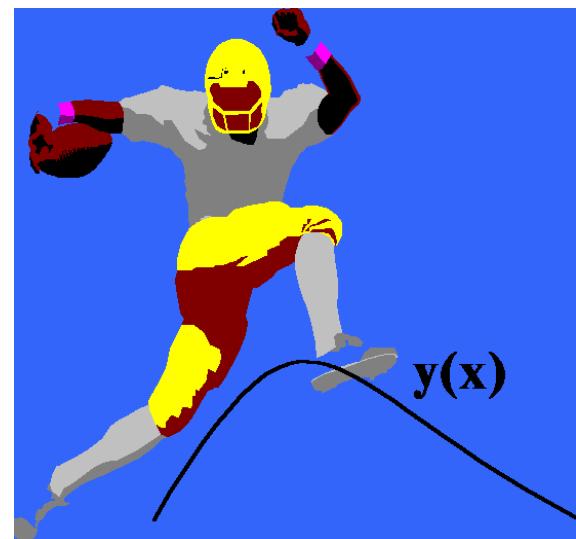


Fig. 13.5. Dependence of the vibration acceleration (curve 1) and pressure (curve 2) on depth (in relative units): (a) $f = 31.5 \text{ Hz}$; (b) $f = 125 \text{ Hz}$

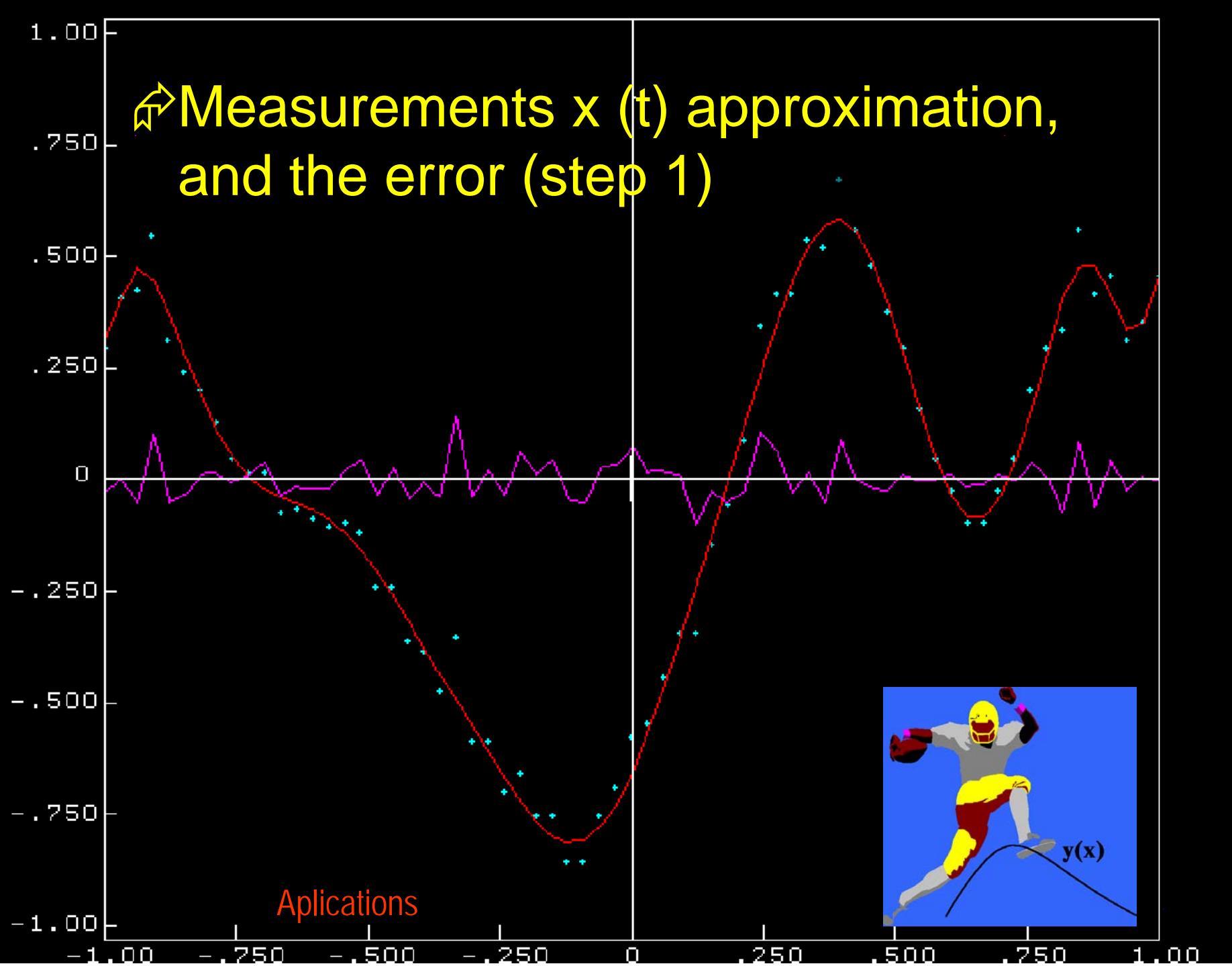
Biomechanical data analysis

- Kinematics of human body

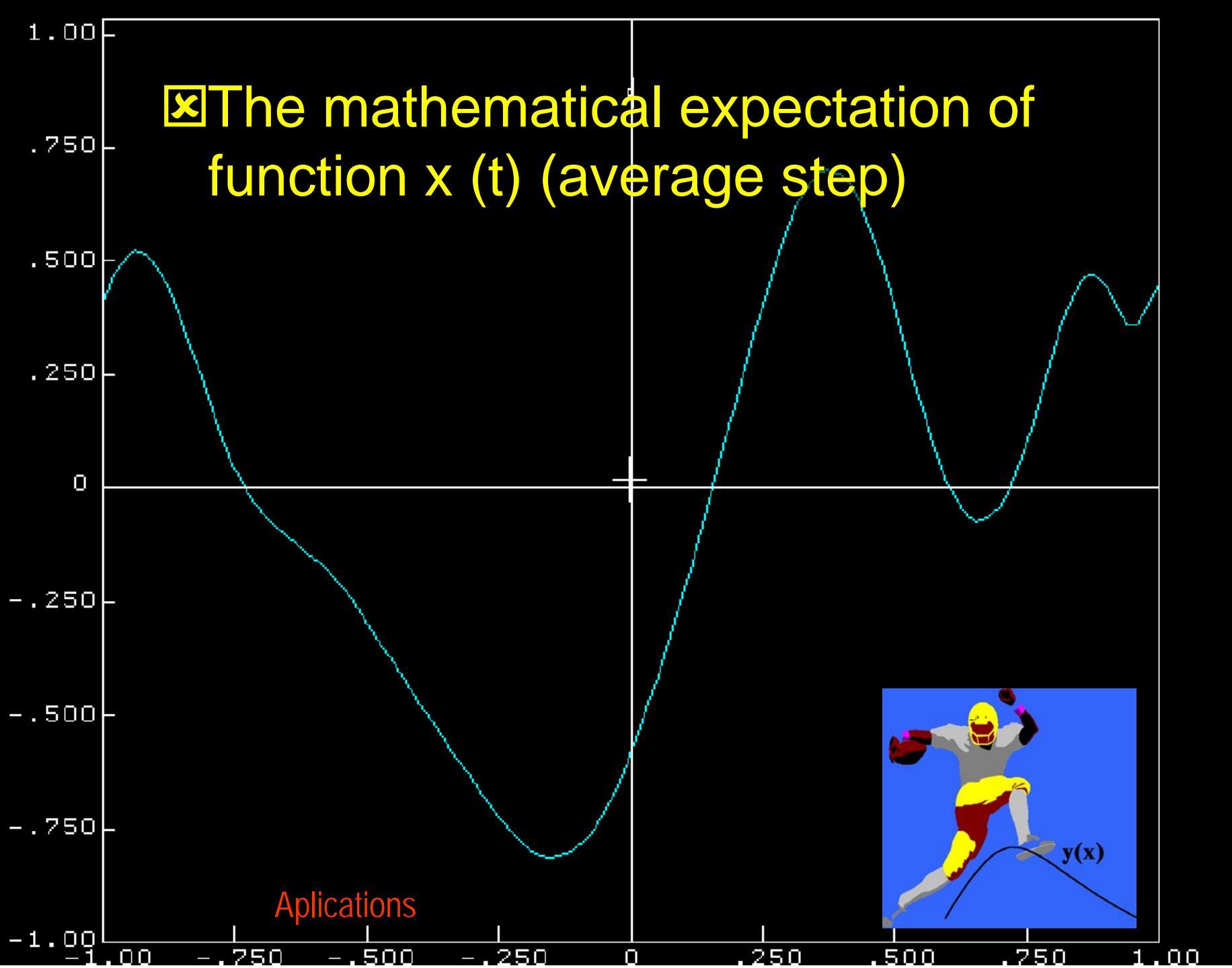
Applications



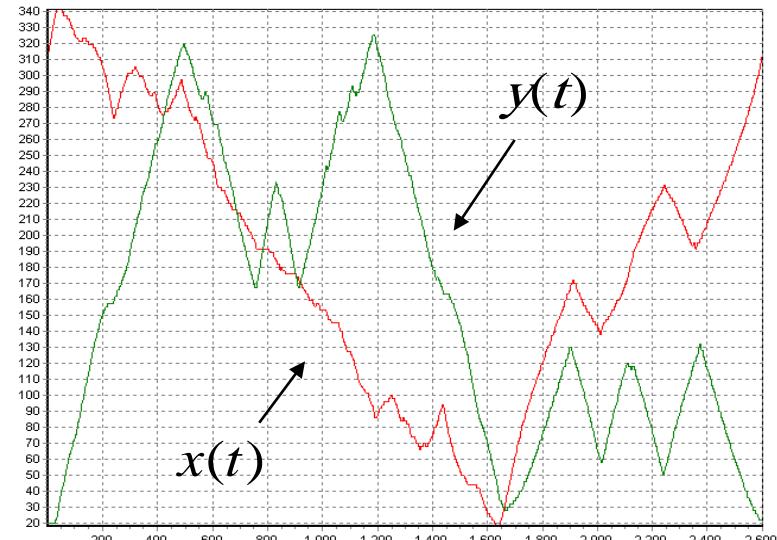
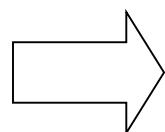
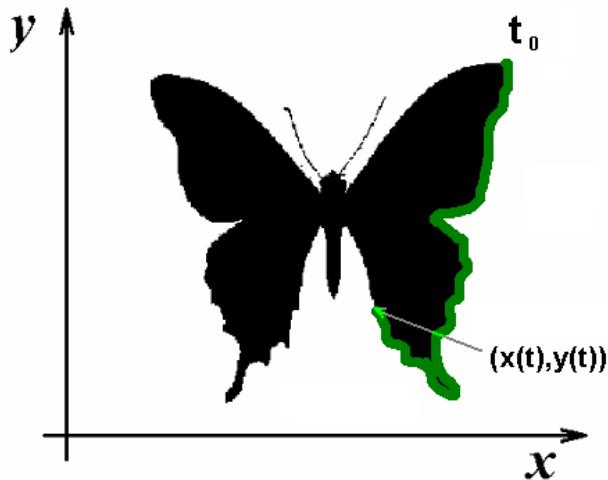
↗ Measurements $x(t)$ approximation,
and the error (step 1)



The mathematical expectation of
function $x(t)$ (average step)



Example of parametric description

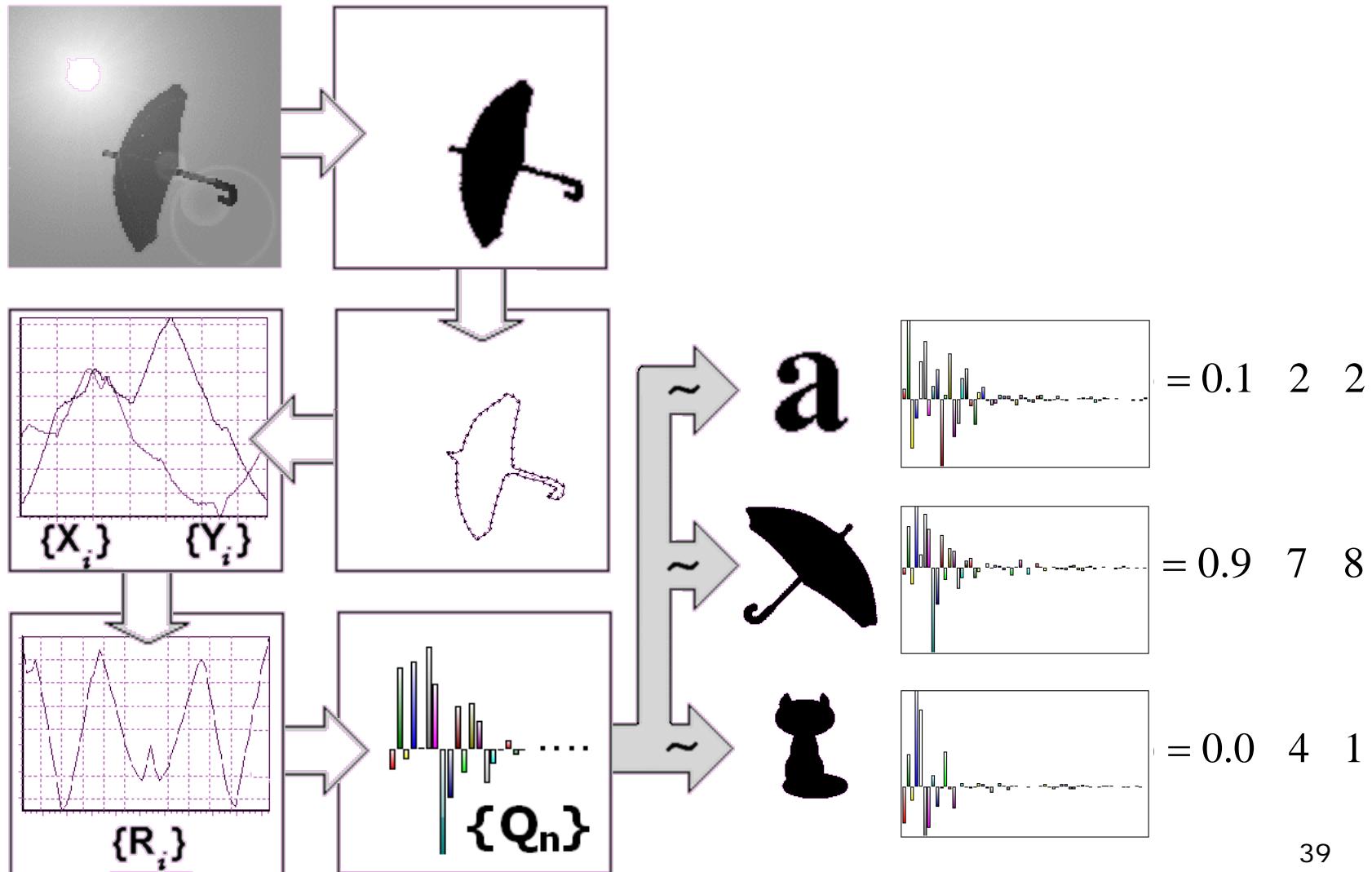


	0	1	2	3	4	...	
A_n	91.2	568	141	-148	-30		$\sum_{n=1}^N \sqrt{A_n^2 + B_n^2}$
B_n	76.6	-318	342	-107	-68		
$\sqrt{A_n^2 + B_n^2}$		651	370	182	74.7		1317

$$x(t) = \sum_{n=0}^N A_n \varphi_n(t);$$

$$y(t) = \sum_{n=0}^N B_n \varphi_n(t).$$

The general scheme of objects comparison



Coclusions

The information technology solves the following tasks:

- analytical description of the different nature signals
- spectral data conversion using the developed mathematical libraries
- systems assessment and recognition of abnormal behavior
- time series analysis and the search for sites with desired properties
- noise filtering, direct and reverse integral-differential problems solving

Děkuji za pozornost!